



EMC Data Sheet

***Unidrive-M
series Frame
size 3
All models***

Variable Speed AC
drive for induction
and permanent
magnet motors

Unidrive-M Frame size 3 EMC Data Sheet

Safety Warnings



A Warning contains information which is essential for avoiding a safety hazard.



A Caution contains information which is necessary for avoiding a risk of damage to the product or other equipment

NOTE:

A Note contains information which helps to ensure correct operation of the product.

Installation and Use

The information given in this data sheet is derived from tests and calculations on sample products. It is provided to assist in the correct application of the product, and is believed to correctly reflect the behaviour of the product when operated in accordance with the instructions. The provision of this data does not form part of any contract or undertaking. Where a statement of conformity is made with a specific standard, the manufacturer takes all reasonable measures to ensure that its products are in conformance. Where specific values are given these are subject to normal engineering variations between samples of the same product. They may also be affected by the operating environment and details of the installation arrangement.

The manufacturer accepts no liability for any consequences resulting from inappropriate, negligent or incorrect installation of the equipment.

The contents of this data sheet are believed to be correct at the time of printing. The manufacturer reserves the right to change the specification of the product or its performance, or the contents of the data sheet, without notice.



All electrical installation and maintenance work must be carried out by qualified electricians, familiar with the requirements for safety and EMC. The installer is responsible for ensuring that the end product or system complies with all relevant laws in the country where it is used.

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1. Products

This EMC data sheet applies to the following products:

Table 1 Model numbers

Supply voltage (V)	Motor power (kW)	Drive Application				
		Machinery control	High speed	Elevator drive	Powerdrive (fans and pumps)	HVAC drive
200	0.75/ 1.1	Mxxx-032 00050A	HSxx-032 00050A		F300-032 00066A	H300-032 00066A
200	1.1/ 1.5	Mxxx-032 00066A	HSxx-032 00066A		F300-032 00080A	H300-032 00080A
200	1.5/ 2.2	Mxxx-032 00080A	HSxx-032 00080A	Exxx-032 00106A	F300-032 00110A	H300-032 00110A
200	2.2/ 3.0	Mxxx-032 00106A	HSxx-032 00106A		F300-032 00127A	H300-032 00127A
400	0.75/ 1.1	Mxxx-034 00025A	HSxx-034 00025A		F300-034 00034A	H300-034 00034A
400	1.1/ 1.5	Mxxx-034 00031A	HSxx-034 00031A		F300-034 00045A	H300-034 00045A
400	1.5/ 2.2	Mxxx-034 00045A	HSxx-034 00045A	Exxx-034 00062A	F300-034 00062A	H300-034 00062A
400	2.2/ 3.0	Mxxx-034 00062A	HSxx-034 00062A	Exxx-034 00078A	F300-034 00077A	H300-034 00077A
400	3.0/ 4.0	Mxxx-034 00078A	HSxx-034 00078A	Exxx-034 00100A	F300-034 00104A	H300-034 00104A
400	4.0/ 5.5	Mxxx-034 00100A	HSxx-034 00100A		F300-034 00123A	H300-034 00123A

Where:

Mxxx denotes M600, M700, M701, M702, M708 or M709

HSxx denotes HS70, HS71 or HS72.

Exxx denotes E200 or E300

The drive rated power e.g. 0.75/ 1.1 denotes Heavy Duty/ Normal Duty.

Products with the same rated voltage and power are identical in construction. The displays, user menus and firmware are optimised for particular applications.

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2. Immunity

2.1.1 Immunity Compliance

References to IEC standards are used throughout this EMC data sheet. In the EU, the applicable standard is the equivalent harmonised EN standard.

Table 2 Immunity test levels

Standard	Type of immunity	Test specification	Application	Level
IEC 61000-4-2	Electrostatic discharge	6 kV contact discharge 8 kV air discharge	Module enclosure	Level 3 (industrial)
IEC 61000-4-3	Radio frequency radiated field	Prior to modulation: 10 V/m 80 - 1000 MHz 3 V/m 1.4 - 2.0 GHz 1 V/m 2.0 - 2.7 GHz 80% AM (1 kHz) modulation Safe Torque Off (STO) tested to : 20 V/m 80 - 1000 MHz 6 V/m 1.4 - 2.0 GHz 3 V/m 2.0 - 2.7 GHz	Module enclosure	Level 3 (industrial)
IEC 61000-4-4	Fast transient burst	5 / 50 ns 2 kV transient at 5 kHz repetition frequency via coupling clamp	Control lines	Level 4 (industrial harsh)
		5 / 50 ns, 2 kV transient at 5 kHz repetition frequency by direct injection	Power lines	Level 3 (industrial)
IEC 61000-4-5	Surges	Common mode 4 kV 1.2 / 50 μ s wave shape	AC supply lines: line to earth	Level 4
		Differential mode 2 kV	AC supply lines: line to line	Level 3
		Common mode 1 kV	Control lines	(Note:1)
IEC 61000-4-6	Conducted radio frequency	10 V prior to modulation 0.15 - 80 MHz 80% AM (1 kHz) modulation	Control and power lines	Level 3 (industrial)
IEC 61000-4-11	Voltage dips, short interruptions & variations	All durations	AC supply lines	
IEC 61000-4-8	Power frequency magnetic field	1700 A/m RMS. 2400 A/m peak (2.1 mT RMS 3 mT peak) continuous at 50 Hz	Module enclosure	Exceeds level 5 (Note: 2)
IEC 61000-6-1	Generic immunity standard for the residential, commercial and light - industrial environment			Complies
IEC 61000-6-2	Generic immunity standard for the industrial environment			Complies
IEC 61800-3	Product standard for adjustable speed power drive systems (immunity requirements)		Meets immunity requirements for first and second environments	

Notes:

1 Applies to ports where connections may exceed 30 m length. Special provisions may be required in some cases – see additional information below.

2 Limited by test equipment capability

Unless stated otherwise, immunity is achieved without any additional measures such as filters or suppressors. To ensure correct operation, the wiring guidelines specified in the Power Installation Guide must be followed. All inductive components such as relays, contactors, electromagnetic brakes must be fitted with appropriate suppression.

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2.1.2 Surge immunity of control circuits

The input/output ports for the control circuits are designed for general use within machines and small systems without any special precautions.

These circuits meet the requirements of IEC 61000-6-2 (1 kV surge) provided that the 0 V connection is not earthed. In general the circuits cannot withstand the surge directly between the control lines and the 0 V connection.

The surge test simulates the effect of a lightning strike, or a severe electrical fault, where high transient voltages may exist between different points in the grounding system. This is a particular risk where the circuits are routed outside a building, or if the grounding system in a building is not well bonded.

In applications where control circuits are exposed to high-energy voltage surges, some special measures are required to prevent malfunction or damage. In general, circuits that are routed outside the building where the drive is located, or are longer than 30 m need additional protection. One of the following techniques should be used:

1. Galvanic isolation, Do not connect the control 0 V terminal to ground. Avoid loops in the control wiring, i.e. ensure every control wire is routed next to its associated return (0 V) wire.
2. Screened cable. The cable screen may be connected to ground at both ends. In addition the ground conductors at both ends of the cable must be bonded together by a power ground cable (equal potential bonding cable) with cross-sectional area of at least 10 mm². This ensures that in the event of a fault, the fault current flows through the ground cable and not through signal cable screen. If the building or plant has a well-designed common bonded network this precaution is not necessary.
3. Additional over-voltage suppression. This applies to analogue and digital inputs and outputs. A zener diode network or a commercially available surge suppressor may be connected between the signal line and 0 V as shown in Figures 1 and 2.

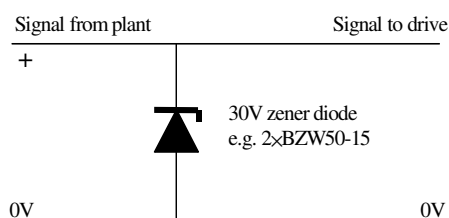


Figure 1 Surge suppression for digital and unipolar analogue inputs and outputs

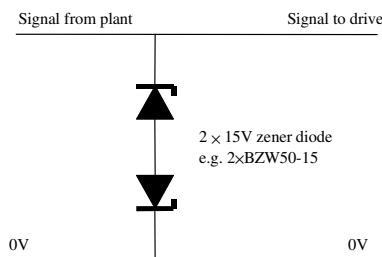


Figure 2 surge suppression for bipolar analogue inputs and outputs

Surge suppression devices are available as rail-mounting modules, e.g. from Phoenix Contact GmbH:

Unipolar	TT-UKK5-D/24 DC
Bipolar	TT-UKK5-D/24 AC

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These devices are not suitable for encoder signals or fast digital data networks because the capacitance of the zener diodes adversely affects the signal. Most encoders have galvanic isolation of the signal circuit from the motor frame, in which case no precautions are required. For data networks, follow the specific recommendations for the particular network.

3. Emission

3.1 General

Emission occurs over a wide range of frequencies. The effects are divided into three main categories:

- Low frequency effects, such as supply harmonics and notching.
- High frequency emission below 30 MHz where emission is predominantly by conduction.
- High frequency emission above 30 MHz where emission is predominantly by radiation.

3.1.1 Environment and Equipment Categories

The EMC product standard for variable speed drives, IEC 61800-3 defines two environments and four equipment categories:

- First Environment - This includes domestic premises, and establishments that share a low-voltage power supply network with buildings used for domestic purposes. Examples include: houses, apartment buildings, shops, commercial property and industrial premises that share a supply with nearby residential property.
- Second Environment - This includes all establishments other than those directly connected to a low-voltage power supply network which supplies buildings used for domestic purposes. Examples include Factories, industrial plants and areas of any building supplied by a dedicated transformer.
- Equipment Category C1 - Equipment that is intended for use in the First Environment
- Equipment Category C2 - Equipment that is neither a plug-in device nor a movable device. This type of equipment may be used in the First Environment if installed and commissioned by a professional (i.e. person or organisation having the necessary skills to install and commission power drive systems, including EMC requirements).
- Equipment Category C3 - Equipment that is intended only for use in the Second Environment. The equipment is not intended for use in the First Environment
- Equipment Category C4 - Equipment with rated voltage ≥ 1000 V or rated current ≥ 400 A or intended for use as part of a complex system. This equipment is intended only for use in the Second Environment.

The drives are capable of meeting the requirements of Equipment Category C3 without external filters or line reactors. They are capable of meeting the requirements of Equipment Category C2 when installed with external EMC filters and line reactors.

NOTE:	<i>In a domestic environment this product may cause radio interference in which case supplementary mitigation measures may be required.</i>
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Examples of supplementary mitigation measures include additional filtering, a dedicated supply transformer and use of screened cables.

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3.2 Low Frequency Emissions

3.2.1 Supply voltage notching

The drives do not cause notching of the supply voltage.

3.2.2 Voltage fluctuations and flicker

When running at constant load the drive does not generate voltage fluctuations or flicker. Care must be taken to ensure that the application does not cause the load to vary rapidly, resulting in flicker. Cyclical variations with frequency in the region of 2 Hz to 20 Hz are likely to cause irritating lighting flicker and should be avoided.

When power is first applied the drive draws an inrush current which is lower than the rated input current. This meets the requirements of IEC 61000-3-3.

3.2.3 Common mode harmonic emissions (crosstalk)

The drives generate switching waveforms with frequency components in the audible range as well as the frequency range commonly used by telephone and data systems. The installation instructions include recommendations for segregation and shielding of power and signal cables. Refer to the installation instructions contained in the drive Power Installation Guide and in section 4 of this data sheet.

3.2.4 Supply harmonics

The drive input current contains harmonics of the supply frequency. The harmonic levels are affected to some extent by the supply impedance (fault current level). Table 4 shows the levels calculated with a fault level of 5 kA (which is typical of a light industrial installation). This meets and exceeds the requirements of IEC 61800-3. In installations where the fault level is lower and the harmonic current is more critical, the harmonic currents will be lower. The calculations have been verified by laboratory measurements on sample drives.

Note that the RMS current in the table may differ from the maximum specified in the installation guide, since the latter is a worst case value provided for safety reasons which takes account of supply voltage imbalance. The motor efficiency also affects the current. A standard IE2, 4 pole motor has been assumed. For balanced sinusoidal supplies, all even and triple harmonics are absent. The supply voltages used for the calculations are 200 V and 400 V at 50 Hz. The harmonic percentages do not change substantially for other voltages and frequencies within the drive specification.

3.2.5 Input line reactors (line chokes)

Where necessary, a reduction in harmonic current levels can be obtained by fitting reactors in the input supply lines to the drive. This also gives increased immunity to supply disturbances such as voltage surges caused by the switching of high-current loads or power factor correction capacitors on the same supply circuit

Table 5 shows the harmonic currents when the drives are fitted with the line reactors specified in Table 3 below.

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Table 3 Recommended line reactors

Drive rated voltage (V)	Drive rated power (kW)	Line reactor inductance (μH)	Line reactor rated current (A)	Line reactor Model No.	Line reactor Part No.
200	0.75 / 1.1	790	13.5	INL2001	4401-0143
200	1.1 / 1.5	790	13.5	INL2001	4401-0143
200	1.5 / 2.2	480	20.6	INL2002	4401-0144
200	2.2 / 3.0	480	20.6	INL2002	4401-0144
400	0.75 / 1.1	2940	6.6	INL4001	4401-0148
400	1.1 / 1.5	2940	6.6	INL4001	4401-0148
400	1.5 / 2.2	1620	9.1	INL4002	4401-0149
400	2.2 / 3.0	1120	13.0	INL4011	4401-0234
400	3.0 / 4.0	1120	13.0	INL4011	4401-0234
400	4.0 / 5.5	1050	15.8	INL4003	4401-0151

The line reactors cause a slight reduction in the input voltage at the drive terminals, which will normally still permit the full rated torque to be developed in a standard motor. Higher inductance values should not be used unless some reduction of available torque at maximum speed is acceptable. Lower values can be used, and the resulting harmonics currents can be estimated by linear interpolation between the values for no inductance and the inductance value in the tables below. The reactor RMS current rating must be at least equal to the value shown in the table, and the peak current rating should be twice the RMS value in order to avoid magnetic saturation.

3.2.1 Effect of load on harmonics

With reducing load, the major harmonics fall in absolute magnitude, although they generally rise as a fraction of the fundamental. Note that it is mechanical load power that controls input current, i.e. the product of torque and speed. As the speed is reduced, the motor current becomes increasingly reactive so the drive input current falls, together with its harmonics

3.2.2 Product family standards for harmonics

IEC 61000-3-2

This standard applies to equipment rated $\leq 16\text{A}$ per phase with a supply voltage of 230/ 400V, 50 Hz. When applied to equipment for professional use this standard sets harmonic limits for ratings below 1 kW input power. The input power of the 0.75 kW rated drives exceeds 1 kW at full load because the typical motor efficiency is 70 %. Therefore, all of the drives covered by this data sheet are outside the scope of this standard.

IEC 61000-3-12

This standard applies to equipment rated $> 16\text{ A}$ and $\leq 75\text{ A}$ per phase. The 200 V drives with power ratings 1.5 kW, 2.2 kW, 3 kW and 4 kW and the 400 V drives with power ratings 5.5 kW and 7.5 kW fall within the scope of this standard. Table 6 shows the harmonic currents when the drives are fitted with the minimum line reactance (inductance) necessary to comply with this standard.

3.2.3 Note on load power for IEC 61000-3-12 compliance

The value of the required input reactor depends upon the load power, i.e. the product of shaft speed and torque. The values given above are correct for the stated load, which is a standard 4-pole IE2 induction motor delivering the specified load power. If the actual maximum continuous electrical load is less than this, the inductance must be scaled up in inverse proportion to the actual load. When carrying out tests according to IEC 61000-3-12, it is important to arrange for the equipment to be fully loaded in order to obtain valid results.

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EN 12015 Product family standard for lifts, escalators and moving walks - Emission

The scope of this standard extends to equipment rated less than 16 A per phase. The harmonic current limits are the same as in EN 61000-3-12:2005. The harmonic reference current used is the fundamental current of the complete lift system. With the line reactor values shown in Table 6 fitted, the drives meet the limits in the standard for $R_{SCE} \geq 250$.

Note: R_{SCE} is the short-circuit ratio. It is the ratio of the short circuit power of the supply to the rated apparent power of the variable speed drive.

3.2.4 Further measures for reducing harmonics

It is unusual for harmonics to pose a problem unless more than 50% of the supply system capacity is accounted for by drives or other power electronic loads. Harmonic currents from drives add approximately arithmetically. It is usually most cost-effective to analyse a complete installation for harmonic current or voltage and to apply remedial measures such as harmonic filters, if necessary, for the entire installation at the common supply point.

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Table 4 Harmonic currents without line reactor

Rated voltage (V)	Motor Power (kW)	RMS current (A)	Fund. current (A)	THD (%)	PWHd (%)	Harmonic order, magnitude as % of fundamental																DPF Cos Ø	Power Factor
						5	7	11	13	17	19	23	25	29	31	35	37	41	43	47	49		
200	1.1	7.67	4.3	149.45	151.95	90.91	82.47	60.70	48.81	26.62	17.59	6.73	5.97	6.62	6.06	3.81	2.84	2.45	2.54	2.22	1.86	0.9934	0.5547
	0.75	6.81	3.7	152.67	167.69	91.42	83.42	62.59	51.07	29.16	19.96	7.82	6.11	6.74	6.47	4.51	3.42	2.57	2.66	2.55	2.23	0.9933	0.5467
200	1.5	9.11	5.2	145.42	133.27	90.23	81.21	58.21	45.86	23.42	14.69	5.86	6.04	6.32	5.43	3.09	2.49	2.58	2.55	1.92	1.56	0.9942	0.5654
	1.1	8.72	4.9	146.53	138.4	90.42	81.57	58.91	46.68	24.29	15.47	6.05	6.03	6.45	5.65	3.30	2.58	2.59	2.61	2.04	1.66	0.9941	0.5625
200	2.2	13.75	8.2	135.64	93.26	88.32	77.72	51.58	38.22	15.80	8.44	5.64	6.23	4.75	3.41	2.20	2.36	2.13	1.72	1.26	1.32	0.9943	0.5918
	1.5	10.34	6	142.31	119.65	89.66	80.17	56.19	43.50	20.96	12.56	5.56	6.16	5.93	4.82	2.61	2.33	2.52	2.35	1.62	1.37	0.994	0.5735
200	3	15.66	9.4	132.9	83.55	87.72	76.62	49.58	35.97	13.75	6.99	5.76	6.10	4.14	2.85	2.27	2.42	1.93	1.49	1.25	1.32	0.9946	0.5998
	2.2	13.30	7.9	136.45	96.02	88.49	78.03	52.17	38.88	16.42	8.89	5.57	6.20	4.87	3.54	2.22	2.38	2.23	1.83	1.25	1.28	0.9942	0.5897
400	1.1	4.78	2.3	179.24	307.05	94.67	89.56	75.48	67.07	49.08	40.14	23.76	16.77	6.09	2.98	3.90	4.71	4.65	4.01	2.30	1.59	0.991	0.4859
	0.75	3.60	1.7	185.07	343.87	95.16	90.50	77.57	69.77	52.80	44.21	28.05	20.93	9.45	5.47	3.48	4.42	5.17	4.87	3.46	2.62	0.9921	0.4749
400	1.5	6.16	3.1	174.1	275.56	94.18	88.62	73.45	64.48	45.60	36.40	19.99	13.24	3.47	1.79	4.17	4.57	3.77	2.92	1.29	1.05	0.9874	0.4949
	1.1	4.39	2.1	181	318.04	94.82	89.85	76.13	67.91	50.23	41.39	25.06	18.02	7.07	3.64	3.74	4.64	4.84	4.30	2.64	1.86	0.9917	0.4826
400	2.2	8.27	4.2	168.7	243.44	93.61	87.54	71.13	61.56	41.78	32.37	16.12	9.72	1.04	2.05	4.12	4.02	2.57	1.62	0.76	1.15	0.9792	0.5023
	1.5	6.16	3.1	174.1	275.56	94.18	88.62	73.45	64.48	45.60	36.40	19.99	13.24	3.47	1.79	4.17	4.57	3.77	2.92	1.29	1.05	0.9874	0.4949
400	3	11.08	6.1	151.89	154.05	91.39	83.36	62.44	50.84	28.65	19.14	5.38	2.68	4.79	4.92	3.28	2.20	1.52	1.81	1.87	1.58	0.9929	0.5482
	2.2	9.08	4.9	155.72	174.43	91.96	84.42	64.58	53.45	31.70	22.13	7.61	3.65	4.63	5.14	4.07	3.02	1.63	1.76	2.10	1.97	0.9941	0.5394
400	4	11.80	8.6	94.74	41.79	74.59	54.42	17.53	7.45	6.44	4.95	2.53	2.70	1.71	1.40	1.30	1.04	0.96	0.90	0.59	0.59	0.9871	0.7177
	3	9.11	6.5	100.14	47.1	77.01	58.30	22.02	10.21	6.74	6.05	2.83	2.70	2.27	1.67	1.50	1.38	0.95	0.95	0.79	0.66	0.9882	0.6995
400	5.5	13.73	10.1	91.63	38.31	73.09	52.08	15.07	6.32	6.06	4.22	2.54	2.57	1.43	1.36	1.12	0.90	0.89	0.73	0.57	0.58	0.9862	0.7282
	4	11.39	8.3	95.43	42.43	74.91	54.94	18.09	7.73	6.50	5.12	2.54	2.69	1.74	1.40	1.35	1.08	0.92	0.88	0.61	0.61	0.9872	0.7153

Note: Shaded cells are for Heavy Duty Mode. Unshaded cells are for Normal mode.

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Table 5 Harmonic currents with line reactor

Rated voltage (V)	Motor Power (kW)	RMS current (A)	Fund. current (A)	THD (%)	PWHd (%)	Harmonic order, magnitude as % of fundamental																AC line choke nom (μH)	DPF Cos Ø	Power factor
						5	7	11	13	17	19	23	25	29	31	35	37	41	43	47	49			
200	1.1	5.69	4.2	91.35	46.36	72.65	51.48	15.50	8.39	7.11	4.98	3.32	3.11	1.86	1.79	1.42	1.19	1.07	0.90	0.80	0.76	790	0.979	0.724
	0.75	5.05	3.7	94.42	49.88	74.16	53.82	17.71	9.12	7.55	5.66	3.34	3.30	2.08	1.80	1.60	1.32	1.15	1.03	0.79	0.81	790	0.9805	0.7141
200	1.5	6.74	5.1	87.05	41.37	70.40	48.09	12.74	7.91	6.30	4.10	3.27	2.73	1.76	1.74	1.22	1.15	0.90	0.78	0.76	0.64	790	0.9771	0.7381
	1.1	6.45	4.8	88.15	42.68	70.99	48.97	13.39	7.97	6.55	4.33	3.27	2.83	1.79	1.77	1.23	1.13	0.97	0.81	0.75	0.66	790	0.9777	0.7345
200	2.2	10.11	8	76.73	29.77	64.40	39.59	8.36	7.82	4.10	3.21	2.43	1.81	1.57	1.24	1.05	0.90	0.75	0.70	0.52	0.55	790	0.971	0.7713
	1.5	7.64	5.9	83.89	37.77	68.66	45.52	11.02	7.82	5.64	3.64	3.12	2.39	1.78	1.64	1.15	1.12	0.82	0.79	0.66	0.56	790	0.9756	0.7484
200	3	12.18	9.3	84.73	37.04	69.22	46.30	11.13	7.32	5.63	3.55	3.02	2.37	1.67	1.59	1.08	1.07	0.78	0.73	0.65	0.54	480	0.9772	0.7465
	2.2	10.38	7.8	88.62	41.67	71.32	49.43	13.47	7.54	6.44	4.25	3.14	2.77	1.70	1.70	1.21	1.09	0.94	0.78	0.74	0.65	480	0.9791	0.7338
400	1.1	3.10	2.3	92.53	45.34	73.32	52.50	16.18	8.10	6.97	5.00	3.12	3.03	1.81	1.67	1.41	1.16	1.05	0.90	0.75	0.75	2940	0.981	0.7212
	0.75	2.36	1.7	99.03	52.13	76.35	57.28	21.24	10.50	7.61	6.39	3.25	3.19	2.43	1.85	1.68	1.49	1.12	1.10	0.82	0.73	2940	0.9835	0.7001
400	1.5	3.98	3	86.73	38.69	70.34	47.96	12.25	7.23	5.93	3.78	3.07	2.55	1.63	1.62	1.13	1.08	0.83	0.73	0.72	0.60	2940	0.9782	0.74
	1.1	2.85	2.1	94.46	47.41	74.26	53.96	17.64	8.66	7.21	5.43	3.11	3.12	1.96	1.68	1.51	1.24	1.09	0.97	0.73	0.75	2940	0.9818	0.7149
400	2.2	5.74	4.2	95.49	44.01	74.88	54.91	18.25	8.15	6.71	5.25	2.71	2.81	1.83	1.48	1.40	1.13	0.97	0.92	0.64	0.64	1620	0.9857	0.714
	1.5	4.30	3	101.66	49.88	77.60	59.29	23.35	11.36	7.01	6.43	3.12	2.81	2.46	1.85	1.55	1.47	0.99	0.96	0.85	0.70	1620	0.9872	0.6936
400	3	8.18	6	92.36	42.7	73.33	52.49	15.86	7.41	6.64	4.76	2.86	2.82	1.66	1.56	1.31	1.04	0.98	0.85	0.68	0.67	1120	0.9829	0.7232
	2.2	6.74	4.9	96.73	47.33	75.40	55.74	19.29	9.01	7.10	5.70	2.91	2.99	2.07	1.61	1.51	1.27	1.05	1.01	0.69	0.67	1120	0.9845	0.7088
400	4	10.24	8.5	68.32	26.57	57.95	34.39	7.02	6.65	3.52	2.79	2.20	1.59	1.52	1.10	1.10	0.83	0.86	0.65	0.64	0.55	1120	0.9744	0.8053
	3	8.11	6.4	78.38	29.69	65.38	41.28	8.27	7.37	4.16	3.07	2.45	1.81	1.50	1.33	0.96	0.97	0.66	0.81	0.44	0.62	1120	0.9734	0.7671
400	5.5	11.78	10	62.89	26.11	53.93	30.52	7.03	5.89	3.54	2.56	2.21	1.53	1.53	1.09	1.10	0.84	0.84	0.65	0.62	0.55	1050	0.9764	0.8272
	4	10.06	8.2	72.54	27.03	61.06	37.42	6.93	7.19	3.47	3.00	2.19	1.65	1.52	1.14	1.11	0.84	0.88	0.65	0.65	0.56	1050	0.9729	0.7883

Note: Shaded cells are for Heavy Duty Mode. Unshaded cells are for Normal mode.

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Table 6 Harmonic currents with minimum line reactance needed to comply with harmonic current limits in EN 61000-3-12, Table 4 for $R_{SCE} \geq 120$

Rated Voltage (V)	Motor Power (kW)	RMS current (A)	Fund. current (A)	THD (%)	PWHF (%)	Harmonic order, magnitude as % of fundamental																AC line choke nom (μ H)	DPF cos ϕ	Power factor
						5	7	11	13	17	19	23	25	29	31	35	37	41	43	47	49			
200	1.1	4.35	4.1	36.58	18.52	33.85	10.74	6.96	3.40	2.82	1.99	1.33	1.24	0.75	0.76	0.54	0.48	0.43	0.35	0.33	0.30	6000	0.9701	0.9114
	0.75	3.83	3.6	38.79	19.76	35.68	12.13	7.26	3.45	3.07	1.99	1.50	1.30	0.82	0.83	0.56	0.52	0.43	0.36	0.32	0.29	6000	0.9719	0.9064
200	1.5	5.27	4.9	36.46	18.44	33.76	10.65	6.93	3.40	2.80	2.00	1.32	1.23	0.76	0.75	0.55	0.48	0.43	0.36	0.33	0.30	5000	0.97	0.9116
	1.1	5.02	4.7	37.25	18.86	34.42	11.13	7.04	3.41	2.90	1.99	1.38	1.26	0.76	0.78	0.54	0.48	0.44	0.35	0.32	0.30	5000	0.9707	0.91
200	2.2	8.37	7.8	37.38	18.6	34.58	11.15	6.97	3.37	2.87	1.96	1.36	1.24	0.74	0.77	0.54	0.46	0.43	0.34	0.31	0.29	3000	0.9704	0.9094
	1.5	6.24	5.7	43.24	21.72	39.31	15.17	7.61	3.72	3.36	1.99	1.78	1.34	1.03	0.93	0.65	0.64	0.45	0.45	0.35	0.32	3000	0.9736	0.8941
200	3	9.59	9	35.17	17.16	32.72	9.84	6.63	3.35	2.58	1.94	1.18	1.14	0.70	0.67	0.53	0.44	0.40	0.34	0.29	0.27	3000	0.9682	0.9137
	2.2	8.09	7.6	38	19.12	35.09	11.54	7.07	3.39	2.94	1.98	1.42	1.27	0.78	0.80	0.55	0.50	0.44	0.36	0.33	0.30	3000	0.9709	0.908
400	1.1	2.37	2.2	38.45	19.24	35.46	11.86	7.10	3.41	2.96	1.98	1.44	1.27	0.80	0.81	0.54	0.51	0.43	0.36	0.33	0.29	18000	0.9706	0.9064
	0.75	1.78	1.6	44.37	21.94	40.20	16.02	7.65	3.80	3.41	1.98	1.80	1.34	1.06	0.92	0.67	0.65	0.44	0.47	0.34	0.32	18000	0.9733	0.8902
400	1.5	3.12	2.9	37.05	18.34	34.31	10.96	6.86	3.37	2.80	1.96	1.32	1.23	0.74	0.76	0.54	0.47	0.44	0.35	0.33	0.30	15000	0.9692	0.9092
	1.1	2.21	2	43.93	21.73	39.87	15.68	7.59	3.75	3.37	1.98	1.78	1.33	1.03	0.93	0.65	0.64	0.45	0.46	0.35	0.32	15000	0.9731	0.8914
400	2.2	4.30	4	37.31	18.17	34.58	11.05	6.80	3.34	2.77	1.94	1.31	1.22	0.73	0.75	0.54	0.46	0.44	0.34	0.32	0.30	11000	0.9687	0.908
	1.5	3.20	2.9	43.16	21.04	39.32	15.07	7.42	3.62	3.27	1.94	1.69	1.32	0.97	0.89	0.63	0.60	0.42	0.44	0.33	0.30	11000	0.9724	0.8933
400	3	6.20	5.8	35.97	17.51	33.43	10.28	6.67	3.34	2.65	1.93	1.23	1.17	0.70	0.71	0.53	0.44	0.43	0.33	0.31	0.29	8000	0.9682	0.9114
	2.2	5.06	4.7	39.53	19.7	36.38	12.53	7.17	3.42	3.05	1.96	1.50	1.30	0.82	0.84	0.57	0.52	0.44	0.38	0.33	0.31	8000	0.9712	0.9036
400	4	8.82	8.3	35.4	18.44	32.80	10.13	6.79	3.44	2.80	2.02	1.33	1.23	0.74	0.73	0.54	0.47	0.43	0.35	0.32	0.30	5000	0.9715	0.9162
	3	6.74	6.3	40.02	21.22	36.61	13.14	7.33	3.53	3.27	2.04	1.68	1.38	0.95	0.90	0.61	0.58	0.43	0.42	0.34	0.31	5000	0.9748	0.9054
400	5.5	10.45	9.8	35.89	18.93	33.21	10.42	6.85	3.44	2.89	2.04	1.39	1.26	0.76	0.77	0.54	0.48	0.44	0.36	0.33	0.31	4000	0.9724	0.9156
	4	8.61	8	39.19	20.91	35.95	12.56	7.22	3.49	3.22	2.04	1.64	1.37	0.92	0.88	0.60	0.56	0.43	0.40	0.34	0.30	4000	0.9747	0.9079

Note: Shaded cells are for Heavy Duty Mode. Unshaded cells are for Normal mode.

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3.3 Conducted Emissions

3.3.1 General

Radio frequency emission in the range from 150 kHz to 30 MHz is generated by the switching action of the main power devices (IGBTs) and is mainly conducted out of the equipment through electrical power wiring.

In order to comply with emission standards, a shielded (screened) cable must be used to connect the variable speed drive to the motor. Most types of cable are acceptable provided that it has an overall screen that is continuous for its entire length. For example, steel wire armoured cable is acceptable.

3.3.2 Measures to reduce conducted emissions

The following measures can be used to reduce conducted emissions:

- Use the lowest possible switching frequency.
- Use the shortest possible motor cable length
- Follow the installation instructions given in this data sheet

3.3.3 Internal filtering

The drives contain a cost-effective internal input filter which gives a reduction of approximately 30 dB in the level of emission at the supply terminals. This filter (in conjunction with a screened motor cable) is sufficient to meet Equipment Category C3 (See section 3.1 for definition of equipment categories).

The Power Installation Guide gives instructions on how to remove and replace the internal EMC filter.

3.3.4 Use of a ferrite ring

Passing the motor cable through a ferrite ring can reduce conducted emissions.

Two sizes of ferrite ring have been used for testing, as shown in Table 7.

The ferrite ring should be mounted close to the drive, and the output power conductors (U, V and W but not E) should be passed once or twice through the central aperture, all together in the same direction.

Table 7 Ferrite rings

Manufacturer	Manufacturers Part No.	CT Part No.	Dimensions (mm)		
			Outside diameter	Inside diameter	Thickness
Epcos	B64290 L0040 X 830	4200-3608	58.3	40.8	17.6
	B64290 L0048 X 830	4200-0003	34.0	20.5	12.5

3.3.5 External filtering

If the equipment needs comply with the generic standard for emission IEC 61000-6-4 or operate in the First Environment then an external EMC filter is necessary.

Suitable filters are available from Control Techniques. The ratings and part numbers are shown in Table 8.

Table 8 External filter part numbers and ratings

CT Part No.	Rated voltage (V)	Rated Current (A)	Operational leakage current (mA) ¹	Worst case leakage current (mA) ²
4200-3230	250	20	2.4	60
4200-3480	528	16	10.7	151

¹ Calculation with 3% capacitance tolerance

² Calculation with two phases open circuit

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In practice, the external filter should always be used in conjunction with the internal filter. The total earth leakage current with both filters connected may be higher than the figures shown above.

	When either the internal filter, the external filter or both filters are connected, the earth leakage current will exceed 3.5 mA. A permanent fixed earth connection is necessary to avoid an electric shock hazard. Further precautions, such as a supplementary earth connection or earth monitoring system, may also be required.
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3.3.6 Operation with IT (ungrounded) supplies

	Special attention is required when using internal or external EMC filters with ungrounded supplies, because in the event of a ground (earth) fault in the motor circuit the drive may not trip and the filter could be over-stressed. In this case, either the filter must not be used (removed) or additional independent motor ground fault protection must be provided. For details of ground fault protection contact the supplier of the drive.
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Unusual hazards can occur on ungrounded supplies with more than one source, for example on ships. Contact the supplier of the drive for more information.

3.3.7 Conducted emission measured results

Tables 10 and 11 show measured results for conducted emissions under various conditions. The equipment categories C1 to C4 are defined in section 3.1.1.

Table 9 Conducted emissions, 200V models

Filter	Ferrite ring No of turns	Maximum motor cable length (m)	Switching frequency (kHz)					
			3	4	6	8	12	16
Internal	0	2	C3	C3	C4	C4	C4	C4
		5	C4	C4	C4	C4	C4	C4
	1	5	C3	C3	C3	C3	C4	C4
		10	C3	C3	C3	C4	C4	C4
		20	C3	C3	C4	C4	C4	C4
	2	5	C3	C3	C3	C3	C4	C4
		10	C3	C3	C3	C4	C4	C4
		20	C3	C3	C4	C4	C4	C4
External	0	20	C1	C1	C1	C1	C2	C2
		100	C2	C2	C2	C2	C2	C2

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Table 10 Conducted emissions, 400V models

Filter	Ferrite ring No of turns	Maximum motor cable length (m)	Switching frequency (kHz)					
			3	4	6	8	12	16
Internal	0	2	C3	C3	C3	C3	C4	C4
		5	C3	C3	C4	C4	C4	C4
		10	C4	C4	C4	C4	C4	C4
	1	2	C3	C3	C3	C3	C4	C4
		10	C3	C3	C3	C3	C4	C4
		15	C3	C4	C4	C4	C4	C4
		20	C4	C4	C4	C4	C4	C4
	2	10	C3	C3	C3	C3	C4	C4
		15	C3	C4	C4	C4	C4	C4
External	0	20	C1	C1	C1	C1	C2	C2
		100	C2	C2	C2	C2	C2	C2

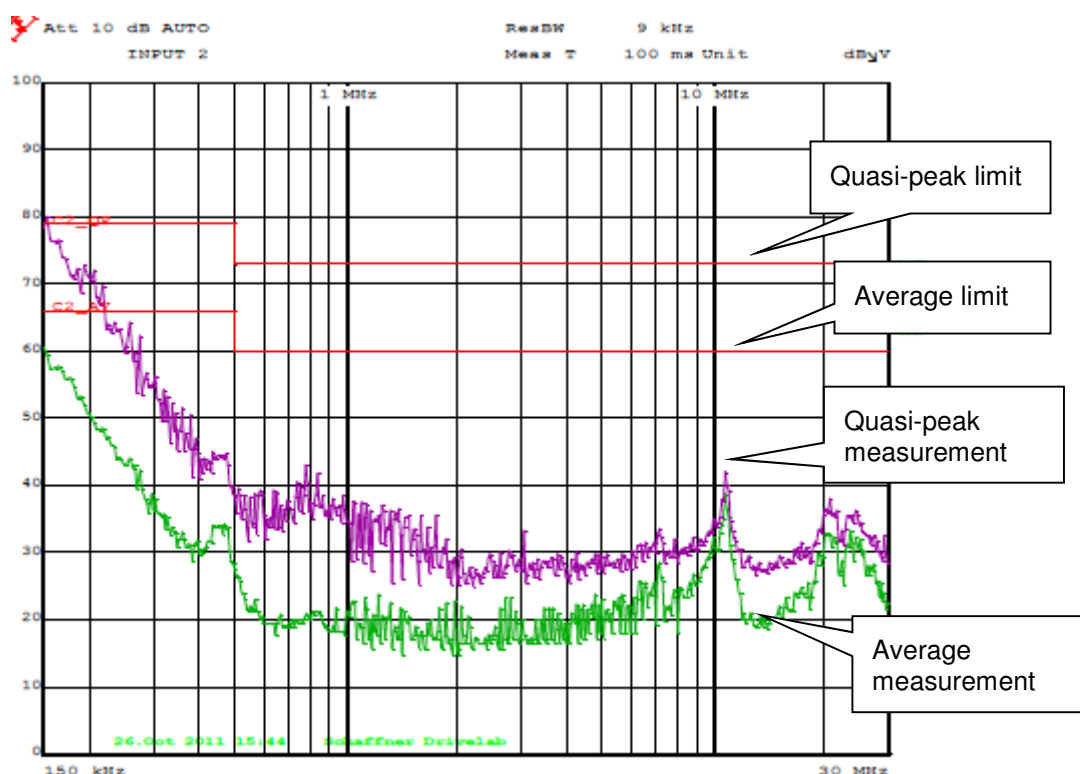


Figure 3 Conducted emission, Model: M700-034 00100A, switching frequency = 3 kHz, motor cable length = 100 m

Notes:

1. Where the drive is incorporated into a system with rated input current exceeding 75 A, the higher emission limits in IEC 61800-3 for the Second environment are applicable, and no filter is required.
2. Operation without a filter is a practical cost-effective option in an industrial environment where existing levels of electrical noise are likely to be high, and any electrical equipment in operation has been designed for such an environment. This is in accordance with IEC 61800-3 for the Second Environment. There is some risk of disturbance to other equipment, and in this case the user and supplier of the drive system must jointly take responsibility for correcting any problems that occur.

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3.3.8 Shared external filters for multiple drives

In multiple drive applications it is preferable to use one EMC filter for each drive. Filters may be shared between drives. However, the applicable motor cable length is the sum of all individual motor cable lengths connected to the same filter.

3.3.9 Related product standards

The conducted emission levels specified in the standards specified above are equivalent to the levels required by the following product specific standards:

Table 11 Comparison of IEC 61800-3 and related emissions standards

Equipment Category in IEC 61800-3	Generic standard	Environment	Product standard	Scope of Product standard
C1	IEC 61000-6-3	Residential, commercial and light-industrial environments	EN 55011 Class B CISPR 11 Class B	Industrial, scientific and medical equipment
			EN 55014 CISPR 14	Household electrical appliances
			EN 55022 Class B CISPR 22 Class B	Information technology equipment
C2	IEC 61000-6-4	Industrial environments	EN 55011 Class A Group 1 CISPR 11 Class A Group 1	Industrial, scientific and medical equipment
			EN 55022 Class A CISPR 22 Class A	Information technology equipment
			EN12015 (rated current ≤ 25 A)	Lifts, elevators and moving walkways

3.4 Radiated Emissions

3.4.1 Industrial emission standard IEC 61000-6-4

When installed in a standard metal enclosure according to the wiring guidelines in section 4 of this EMC data sheet and using the standard or low-leakage mains input filters, the drive will meet the radiated emission limits required by the generic industrial emission standard IEC 61000-6-4.

3.4.2 Limits for radiated emission

Compliance was achieved in tests using representative enclosures and following the guidelines given. Every effort was made to ensure that the arrangements were robust enough to be effective despite the normal variations which will occur in practical installations. However no warranty is given that installations built according to these guidelines will necessarily meet the same emission limits.

The limits for emission required by the generic emission standards are summarised in Table 13.

Table 12 Radiated emissions limits in IEC 61800-3

Frequency range (MHz)	Category C1	Category C2	Category C3	Units
30 - 230	30	40	50	dB μ V/m Quasi peak
230 - 1000	37	47	60	

Note: The limits apply at a measuring distance of 10 m. The measurements may be made at 3 m with the limits increased by 10 dB.

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3.4.3 Example test data

The test data is based on radiated emission measurements made on a standard steel enclosure containing a single drive with three-phase supply. These drives have the highest emission levels in this product range. The tests were carried out in a calibrated open area test site. Details of the test arrangement are described below:

A standard enclosure was used having dimensions 1900 mm (high) × 600 mm (wide) × 500 mm (deep). Two ventilation grilles, both 200 mm square, were provided on the upper and lower faces of the door.

The drive was mounted onto the EMC input filter, which was fitted to the internal back-plate of the enclosure, the filter casing making electrical contact with the back-plate by the fixing screws. Standard unscreened power cables were used to connect the complete unit to the supply.

A suitably rated, standard AC induction motor was connected by 2 m of shielded cable (steel braided - type SY) and mounted externally.

The motor cable screen was clamped to the enclosure back-plate. The motor cable screen was also bonded to the motor frame.

The motor cable was interrupted by a DIN rail terminal block mounted in the enclosure and the shield pigtails (50 mm long) were bonded to the back plate through an earthed DIN rail terminal block.

In addition, the motor cable screen was bonded to the back-plate on both sides of the DIN rail using metal clamps.

A 2 m screened control cable was connected to the drive control terminals with the screen clamped to the enclosure back-plate

A 2 m unscreened status relay cable was connected to the drive.

A 2 m screened communications cable was connected to the drive. The screen was not electrically connected to the drive or cubicle back panel.

The drive was operated at 6 Hz, with a switching frequency of 16 kHz. This is the worst case condition for radiated emission.

No additional EMC preventative measures were taken, e.g. RFI gaskets around the cubicle doors.

The following tables summarise the results for radiated emission, showing the highest measurements over the frequency range 30 MHz to 1000 MHz:

Table 13 Radiated emission measured levels, 200 V (model M600-032 00106A)

Test frequency (MHz)	Measured level (dB μ V/m)	Equipment category C2 limit (dB μ V/m)	Margin (dB μ V/m)
30.0	32.02	40.00	-7.98
31.6	34.13	40.00	-5.87
36.24	30.26	40.00	-9.74
36.72	32.80	40.00	-7.20
37.72	30.75	40.00	-9.25
52.52	31.16	40.00	-8.84
58.88	30.65	40.00	-9.35

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Table 14 Radiated emission measured levels, 400 V (model M600-034 00100A)

Test frequency (MHz)	Measured level (dB μ V/m)	Equipment category C2 limit (dB μ V/m)	Margin (dB μ V/m)
30.0	31.16	40.00	-8.84
30.36	30.97	40.00	-9.03
30.72	30.56	40.00	-9.44
32.24	34.12	40.00	-5.88
53.44	32.66	40.00	-7.34
57.2	28.71	40.00	-11.29

The results show that the limit for industrial radiated emission (C2) is met with a margin of at least 5 dB.

3.4.4 Enclosure construction

In many installations, an enclosure has a back-plate which is used to mount variable speed drives together with the EMC filters and ancillary equipment. The motor cable should be bonded to the back-plate close to the drive before it leaves the enclosure wall. However, there is no disadvantage if the motor cable is bonded at the point of exit as well, through the normal gland fixings.

Depending on construction, the enclosure wall used for cable entry may have separate panels and could make poor electrical contact at high frequencies with the remaining structure. If the motor cable is only bonded to these surfaces and not to a back-plate, then the enclosure may provide insufficient attenuation of RF emission. It is the bonding to a common metal plate which minimises radiated emission. In the tests described, opening the cubicle door had little effect on the emission level, showing that the enclosure design is not critical.

3.4.5 Related product standards

The radiated emission levels specified in IEC 61000-6-4 are equivalent to the levels required by the following product standards:

Table 15 Related radiated emission standards

Generic standard	Product standard	
IEC 61000-6-4	CISPR 11 Class A Group 1 CISPR 11 Class A Group 1	Industrial, scientific and medical equipment
	EN55022 Class A CISPR 22 Class A	Information technology equipment
	EN 12015	Lifts

3.4.6 Radiated emissions test limits for lifts, elevators and moving walkways.

The limits for Radiated Emissions in the standard for Electromagnetic compatibility, Product family standard for lifts, escalators and moving walks, Emission, EN 12015 are the same as those in IEC 61800-3 for equipment category C2.

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4. Installation and Wiring Guidelines

4.1.1 General

The wiring guidelines on the following pages should be observed to achieve minimum emission. The details of individual installations may vary, but details which are indicated in the guidelines to be important for EMC must be adhered to closely. The guidelines do not preclude the application of more extensive measures which may be preferred by some installers. For example, the use of full 360° ground terminations on shielded cables in the place of 'pig-tail' ground connections is beneficial, but not necessary unless specifically stated in the instructions.

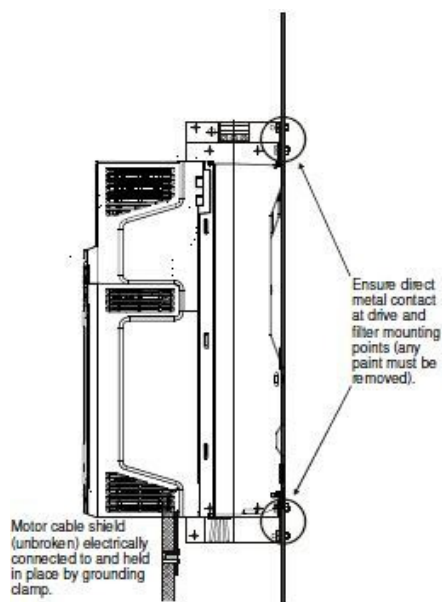


Figure 4 Drive mounted on a footprint filter

If the filter is not used in the “footprint” mode, then the drive and filter must be mounted on the same metal back-plate, and their mounting surfaces must make a good direct electrical connection to it. The use of a plain metal back-plate (e.g. galvanised not painted) is beneficial for ensuring this without having to scrape off paint and other insulating finishes.

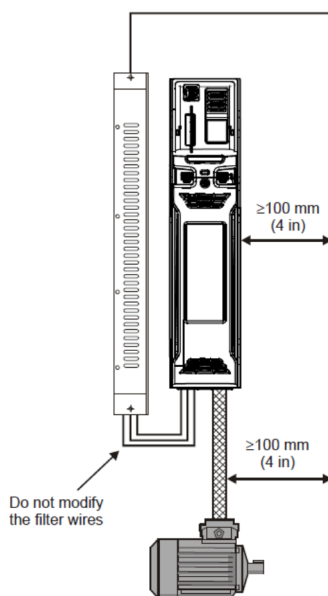


Figure 5 Drive mounted on common back-plate

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1. The correct RFI filter must be fitted at the input to the drive.
2. The limits given above regarding motor cable length and drive switching frequency for the relevant filter must be adhered to.
3. Footprint filter: the drive must be correctly mounted on the filter and make good direct electrical contact with it.
4. Side mounted filter: the drive and filter must be mounted together on a metal back-plate and make good electrical contact with it.
5. The filter must be connected to the drive using the wires provided. The wires must not be extended in any way.
6. The mounting surface of the filter must make good direct electrical contact with the enclosure back-plate. Any paint or other non-conducting surface must be removed.
7. A shielded (screened) or steel wire armoured cable must be used to connect the drive to motor. The shield must be connected to the enclosure back-plate by a good high-frequency connection, for example by direct clamping using a "Ω" clamp or similar.
8. Connect the shield of the motor cable to the ground terminal of the motor frame using a link that is as short as possible and not exceeding 50 mm (2 in) in length. A full 360° termination of the shield to the motor terminal housing (if metal) is beneficial.
9. Ensure that the cables carrying the AC supply and the ground to the filter are at least 100mm (4 in) from the drive and the motor cable.
10. Avoid locating sensitive signal circuits in a zone extending 0.3 m (12 in) all around the drive.
11. If the control circuit 0V is to be grounded, this should preferably be done at the host controller (e.g. PLC) and not at the drive, to avoid injecting noise current into the 0 V circuit.
12. This requirement does not apply if the complete system has been built to a high standard for EMC, using a highly bonded earth arrangement which prevents differential earth noise voltages.

4.1.2 Control wiring leaves the enclosure

The control wiring must be carried in shielded cable (one or more cables) and the shield must be clamped to the enclosure back-plate.

4.1.3 Interruptions to the motor cable

The motor cable should ideally be a single run of shielded cable having no interruptions. In some situations it may be necessary to interrupt the cable, for example to connect the motor cable to a terminal block within the drive enclosure, or to fit an isolator switch to allow safe working on the motor. In these cases the following guidelines should be observed.

4.1.4 Terminal block within enclosure

The motor cable shields should be bonded to the back-plate using uninsulated cable-clamps which should be positioned as close as possible to the terminal block. Keep the length of unscreened power conductors to a minimum and ensure that all sensitive equipment and circuits are at least 0.3 m (12 in) away from the terminal block. See Figure 6.

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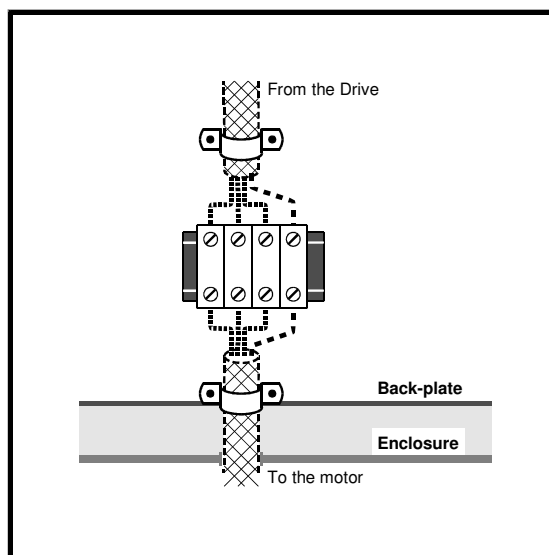


Figure 6 Arrangement for terminal block in motor cable

4.1.5 Using a motor isolator switch

The motor cable shields should be connected by a very short conductor having a low inductance. The use of a flat metal bar is recommended; conventional wire is not suitable. The shields should be bonded directly to the coupling bar using un-insulated metal cable-clamps. Keep the length of the power conductors to a minimum and ensure that all sensitive equipment and circuits are at least 0.3 m (12 in) away. The coupling bar may be grounded to a known low impedance ground nearby, for example a large metallic structure which is connected closely to the Drive ground. See Figure 7.

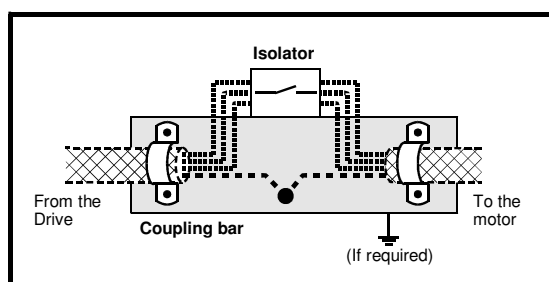


Figure 7 Arrangement for isolator switch in motor cable